
```

% -----inputs-----
f = @(x) exp(x)-x-1;
df = @(x) exp(x)-1; % function derivative
ddf = @(x) exp(x); % function derivative

p0 = 1;
TOL = 1e-5;
NI = 100;
% -----
fprintf("\nModified Newton's Method")

% STEP 1
i = 1;
converge = false; % convergence flag

% STEP 2
while i<=NI
    % STEP 3
    % compute p(i)
    f0 = f(p0);
    df0 = df(p0);
    ddf0 = ddf(p0);
    p = p0-f0*df0/(df0^2-f0*ddf0);
    err = abs(p-p0);
    % STEP 4
    % check if meets the stopping criteria
    if (err< TOL)
        converge = true;
        break
    else
        % STEP 5
        i = i+1;
        % STEP 6
        p0 = p; % update p0
    end
end

if converge
    fprintf('\n\nApproximate solution P = %.8f\n',p)
    fprintf('With F(P) = %.3e\n',f(p))
    fprintf('Number of iterations = %3i\n',i)
    fprintf('Tolerance = %.3e |p-pold| = %.3e\n',TOL, err)
end

```

Modified Newton's Method

```

Approximate solution P = -0.00000000
With F(P) = 0.000e+00
Number of iterations = 5
Tolerance = 1.000e-05 |p-pold| = 0.000e+00

```

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