

SWSSC Project

Design Tools II - Group 9 Cristina Chavez, Jed Cole, Jacob Michels

Design Statement

To design and fabricate an electro-mechanical assembly that mounts to a quadcopter and can obtain and record water samples.

Original Requirements

- Budget: under \$60
- Weight: under 1 pound
- Height: under 6 inches
- Depth: at least 12 inches
- Time: take a picture within 1 minute
- Number of samples: 4

First Build



How Well Original Requirements Were Met

- Budget \$41
- Weight 0.8 lbs
- Height 3.5 inches
- Depth much longer than 12 inches
- Time much less than 1 minute
- Number of samples 4

New Requirements

- 1) Untested sticks must remain dry
- 2) No servos near the water!
- 3) ONLY one strip should appear in each picture the camera takes
- Strip should appear in a reliable position and directly face the camera without being blown by the wind for the photograph
- 5) Long "dangling" strings create hazards
- 6) Strips must be easily replaced between flights
- 7) All parts should be robust for multiple use
- 8) Maximum weight can be up to 1.25 lbs
- 9) Dip stick should sample from a contained space. Dipping into flowing water may wash off the chemical

New Requirements Not Met by Original Design

#5 - Original design used an uncontained, long, dangling string to move the bucket up and down

#6 - Original design had test strip holder that did not have a reliable method to secure strips in place (tape or rubber band)

Improvements

- Spool
- Test Strip Holder
- Bucket
- Telescoping Arm
- Center of Gravity
- Overall Size



- Flimsy
- Larger than needed



- Compact
- Sturdy

Test Strip Holder



- No fastener
- Small
- Strips can easily fall off

- Keeps strips in place
- Has fastener

New

• Sturdy



- Small
- Two holes
- Weights glued on bottom







- Larger, carries more water
- Two handles for string

New

Pocket for weights

Telescoping Arm



- Replaces a long, dangling string
- Prevents swaying
- Keeps CG in the same place
- Compact when retracted

Center of Gravity



- Assigned material properties to each part in assembly
- Placed holes to coincide with CG of the drone

Overall Size



- Size increased to make room for telescoping arm
 - Better spacing between parts



How Well Requirements Were Met

Old Requirements

- Budget \$51
- Weight 1.22 lbs
- Height 4.8 inches
- Depth more than 12 inches
- Time under 1 minute
- Number of samples 4

New Requirements

- 1) Met
- 2) Met
 3) Met
- 4) Met
 5) Met
- 6) Met

8)

9)

Met

Met

Met

How Well Model Worked

- Effectively able to extend to collect water, retract, dip a test strip into bucket, and have a clear path for the GoPro to take a picture
- Met all the requirements

- Telescoping arm created a lot of friction due to the way it printed out
- Is a little difficult to get the bucket submerged
- Parts of assembly are more closely packed than originally thought

Possible Improvements

- Cleaner prints for telescoping arm
 - Possibly with a new material
 - Reduces friction
- Make frame a little bigger to create more spacing

- Telescoping arm retracts on its own without the need for a large disk
 - Would make it easier to get bucket submerged in water